



2022 DRAGON 5 SYMPOSIUM MID-TERM RESULTS REPORTING

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CITID Man

Sentinel-1

Sentinel-2

Sentinel-3

Sentinel-5p

Apolu

Beijing-2

CBERS

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[PROJECT ID. 58817]

[UAVS 4 HIGH-RES. OPTICAL SATS.]



Dragon 5 Mid-term Results Project



THURSDAY 20/10/2022 ID. 58817

PROJECT TITLE: EXPLOITING UAVS FOR VALIDATING DECAMETRIC EARTH OBSERVATION DATA FROM SENTINEL-2 AND GAOFEN-6(UVA4VAL)

PRINCIPAL INVESTIGATORS: PROF YONGJUN ZHANG AND PROF JADU DASH

CO-AUTHORS:

PRESENTED BY: PROF JADU DASH







Project background



- Vegetation biophysical variables such as Leaf Area Index (LAI), Canopy Chlorophyll content (CCC), Fraction of absorbed Photosynthetic Radiation (fAPAR) are important plant and ecosystem status indicators.
- Advances in sensing and retrieval techniques -> suitability in operational use
- Validation is crucial to ensure fit-for-purpose
- Field campaigns are logistically challenging and resource intensive
- Automated measurement the way forward







Project objective: UAV4VAL



- Evaluate the capability of UAVs as a source of reference data for validating decametric surface reflectance and vegetation products, (specific focus on Sentinel-2 and GF-6)
- Transfer knowledge gained from existing ESA-funded projects on fiducial reference measurements (FRM), which focus on traceability and uncertainty evaluation in earth observation validation efforts
- Achieved through collection, processing, and analysis of ground measurements over European and Chinese sites, coinciding with UAV acquisitions





Project objective: UAV4VAL









Project team





Dr Jadu Dash

Dr Yongjun Zhang

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Dr Booker



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National Physical Laborate



Timeline







In-situ data measurements—second round



Overview: 2nd Round of fieldwork

Campaign	Period	Parameters and equipment	Contribution
Taizi Mountain, China (112°48′E-113°03′E, 30°48′N-31°02′N)	02-06-2021	LAI-2200C for LAI collection ASD spectrometer for Spectral data collection DJI Phantom 4 for UAV images collection	Wuhan university
Wytham Woods, UK (51.769265N, 1.329185W)	19-07-2021	SPAD for LCC collection Digital hemispherical photography(DHP)	University of Southampton, National Physical Laboratory (NPL)





Field sites



Wytham Woods, Oxford, UK (1)

- Deciduous broadleaf forest
 - (Oak, Ash, Beech, Hazel, Sycamore)
- Managed research forest with ~75 years of ecological monitoring
- Canopy walkway, Flux tower
- > 200 RS papers at site







In-situ data measurements and requirements



Wytham Woods, Oxford, UK

- leaf sampling and chlorophyll measure
- DHP measure
- CCC = LCC x LAI





Licor LAI-2200



Digital

hemispherical

photography

SPAD Chlorophyll meter





Field sites



Taizi Mountain Hubei Province, China

- Deciduous broadleaf forest
 - (Oak and Maple)
- Designated a national park
- Validation of SPOT 6 and GF2 at site
- > 35 remote sensing papers at site











In-situ data measurements and requirements



Taizi Mountain Hubei Province, China

- Surface reflectance and drone images
 - Ground Hyperspectral measurements (350 2500 nm)
 - DJI Phantom 4 for drone image collection
 - In-suit data collection



Spectralon panel







Method: Overview



Taizi Mountain Hubei Province, China

Step 1	Step 2	Step 3	Step 4	
Acquisition and processing of UAV imagery and in-suit biophysical measurements.	LAI Inversion from UAV imagery through Vegetation Indices (VIs) regression model.	VIs sensitivity test on a Radiative Transfer Model (RTM)-simulated	Sentinel-2 LAI product validated by the UAV based LAI product.	
	LAI product from ESA SNAP software.			





Parametric regression through Vegetation indices(VIs)

Formulas of the four VIs and the evaluation metrics for LAI-VI relationship modelling.

$$NDVI = \frac{\rho_{NIR} - \rho_{Red}}{\rho_{NIR} + \rho_{Red}}$$

$$SAVI = \frac{\rho_{NIR} - \rho_{Red}}{\rho_{NIR} + \rho_{Red} + 0.5} \times 1.5$$

$$ARVI = \frac{\rho_{NIR} - (2\rho_{Red} - \rho_{Blue})}{\rho_{NIR} + (2\rho_{Red} - \rho_{Blue})}$$

$$EVI = \frac{\rho_{NIR} - \rho_{Red}}{\rho_{NIR} + 6\rho_{Red} - 7.5\rho_{Blue} + 1} \times 2.5$$

$$R^{2} = 1 - \frac{\sum_{i=1}^{n} (y_{i} - \hat{y}_{i})^{2}}{\sum_{i=1}^{n} (\hat{y}_{i} - \bar{y})^{2}}$$
$$RMSE = \sqrt{\frac{\sum_{i=1}^{n} (y_{i} - \hat{y}_{i})^{2}}{n - p}}$$
$$MAE = \sum_{i=1}^{n} \left| \frac{y_{i} - \hat{y}_{i}}{n} \right|$$
$$ME = \frac{1}{n} \sum_{i=1}^{n} \left(\frac{y_{i} - \hat{y}_{i}}{y_{i}} \right) \times 10^{4}$$





Method: LAI inversion from Sentinel-2 imagery









Results: UAV Radiometric calibration



UAV images Radiometric calibration



Adding certain number of the radiation control points can effectively control the acc and propagation of errors and improve the accuracy of radiation correction.





UAV-LAI inversion model

- All R^2 >0.8
- The correlation between LAI and VI is good
- ARVI and EVI perform well

VI	Model Evaluation Metrics		
	R^2	RMSE	
NDVI	0.8242	0.5985	
SAVI	0.8401	0.5706	
ARVI	0.8869	0.4801	
EVI	0.8798	0.4947	





Result: UVA-LAI inversion from VIs regression







Result: UVA-LAI inversion from VIs regression



UAV LAI products







Result: VI sensitivity test



- VI-LAI relationships are stable for both UAV and Sentinel-2 sensors
- The large EVI bias was found for high dense vegetation





Result: Sentinel-2 LAI product validation



Validation method based on LAI measured on the ground







Result: Sentinel-2 LAI product validation



Validation method based on UAV LAI product





Result: LAI inversion from Sentinel-2 imagery



Validation method based on LAI measured on the ground

Validation method	Validation index			
vanuation method	MAE	ME	RMSE	
Based on Ground-LAI	0.802	0.853	1.020	
Based on NDVI-LAI UAV product	0.504	0.548	0.586	
Based on SAVI-LAI UAV product	0.486	0.731	0.580	
Based on ARVI-LAI UAV product	0.483	0.554	0.558	
Based on EVI-LAI UAV product	0.472	0.672		





Future plan



- More physical-based inversion methods like Look-up Table(LUT) and Non-parametric regression with machine learning algorithms could be explored in UAV based biophysical parameters retrieval.
- The further acquisition of multispectral and even hyperspectral data from the UAV platform is expected.
- More fieldwork and communication in person from the collaborate institutes are planned.





EO Data Delivery



Data access (list all missions and issues if any). NB. in the tables please insert cumulative figures (since July 2020) for no. of scenes of high bit rate data (e.g. S1 100 scenes). If data delivery is low bit rate by ftp, insert "ftp"

ESA Third Party Missions	No. Scenes	ESA Third Party Missions	No. Scenes	Chinese EO data	No. Scenes
1.		1. Sentinel 2 MSI	10	1.GF-6	4
2.		2. Sentinel 3 OLCI	10	2.GF-6	4
3.		3.		3.	
4.		4.		4.	
5.		5.		5.	
6.		6.		6.	
Total:		Total:		Total:	
Issues:		Issues:		Issues: ftp (for oversea users), colleagues at Wuhan University are helpful.	





European Young scientists contributions in Dragon 5 · Cesa



Name	Institution	Poster title	Contribution
Xuerui Guo	University of Southampton	Vegetation Index Sensitivity Test Based on PROSPECT+SAIL Model – a Preliminary Test Under the UAV4VAL Project	
Harry Morris	University of Southampton	Using A Wireless Quantum Sensor Network To Monitor The Temporal Dynamics Of Vegetation Biophysical Parameters In A Mediterranean Vineyard	



Conclusion



- Project team in-depth communication and regular progress meetings
- Return fieldwork at both Chinese and UK sites, data sharing
- GF6 data processing and biophysical variable extraction
- UAV based LAI retrieval method and validation on Sentinel-2 LAI product



Thank you J.Dash@soton.ac.uk

