



2022 DRAGON 5 SYMPOSIUM

MID-TERM RESULTS REPORTING

17-21 OCTOBER 2022

[PROJECT ID. 59198]

**ABSOLUTE CALIBRATION OF
EUROPEAN & CHINESE SATELLITE
ALTIMETERS ATTAINING FIDUCIAL
REFERENCE MEASUREMENTS STANDARDS
OVER THE 2ND YEAR OF DRAGON5**

**THURSDAY (8:30AM - 9:00AM) & 20/OCT/2022,
1.3.1: CAL/VAL**

ID. 129/1.3.1:1

**PROJECT TITLE: ABSOLUTE CALIBRATION OF EUROPEAN & CHINESE SATELLITE
ALTIMETERS ATTAINING FIDUCIAL REFERENCE MEASUREMENTS STANDARDS**

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MU; XENOFON FRANTZIS; COSTAS KOKOLAKIS; YANG LEI; ILIAS TZIAVOS**

PRESENTED BY: STELIOS P. MERTIKAS



Project Objectives:

Calibrate Satellite altimeters of Europe (S3/S6/CS2) & China (HY-2):

- **ESA Permanent Facility for Altimetry Calibration in Crete, Greece;**
- **Chinese Altimeter Calibration Cooperation Plan.**

Results of Calibration to FRM Standards:

- **To absolute reference signals,**
- **Traceable to SI-standards,**
- **Different & redundant techniques (sea & land),**
- **Various processes, diverse instrumentation, settings etc.**

Report FRM Uncertainty for Satellite Cal/Val Results

Analyse Performance Against Other Missions.





Dragon Altimeter Data:

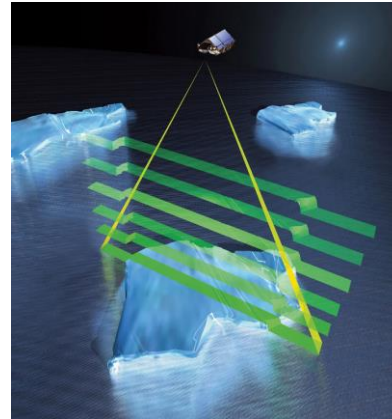
European Satellite Altimeters:



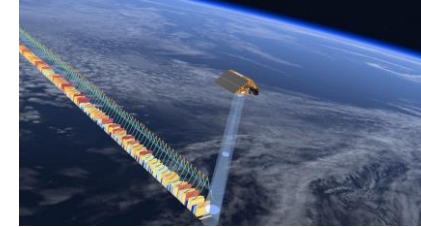
Sentinel-3A (2016)



Sentinel-3B (2018)



CryoSat-2 (2010)



Sentinel-6A (2021)

Chinese Satellite Altimeters:



HY-2B (2018)



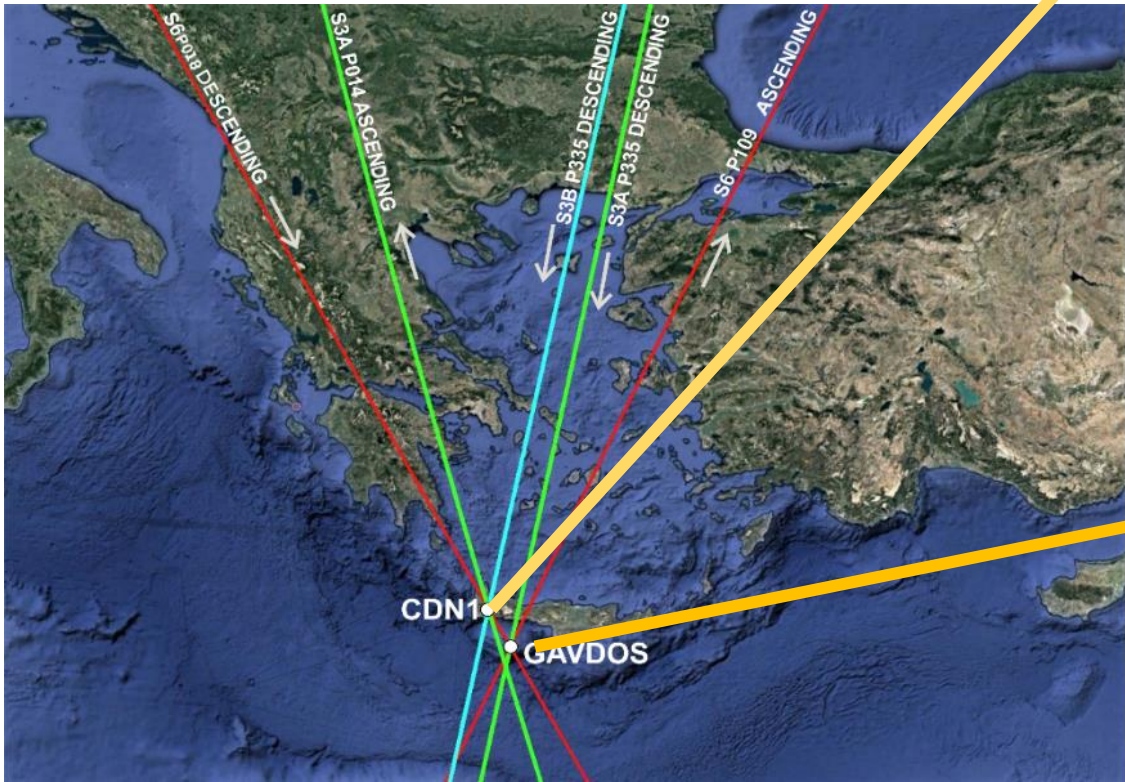
HY-2C (2020)



HY-2D (2021)



Transponders at ESA PFAC, Crete



Crete (CDN1 Transponder)

- Multiple Cross-over (S3A, S3B, Jason-3, S6, AltiKa, SWOT),
- Low clutter,
- Cross-calibration,
- Crystal clear signal of S3 Signals.



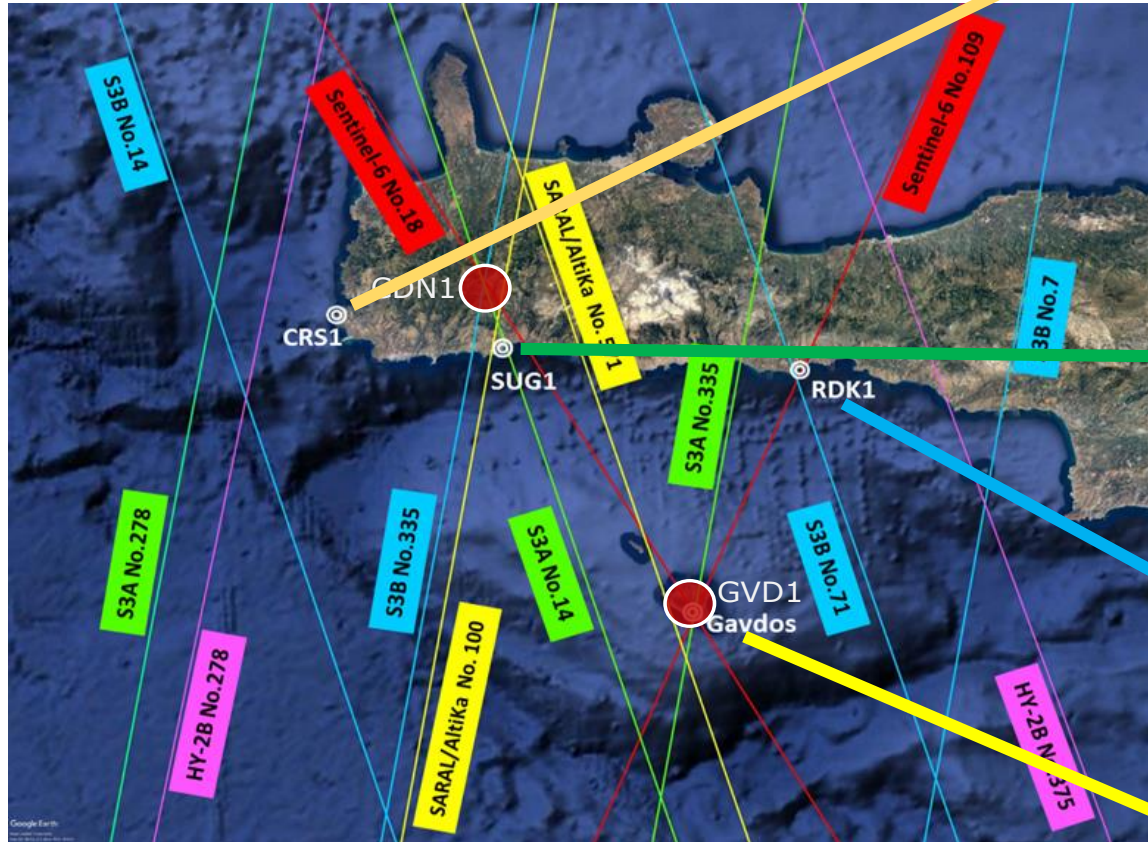
Gavdos (GVD1 Transponder)



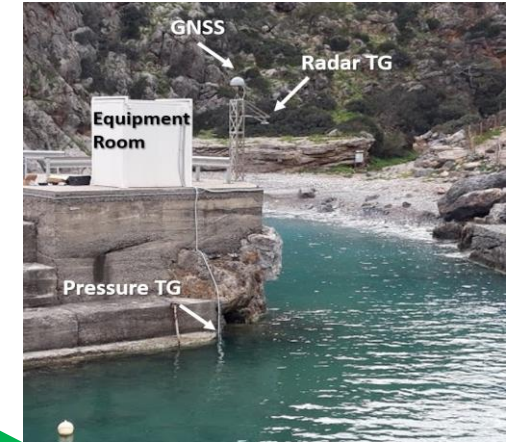
S3A, Sentinel-6 (Ascending & Descending), sea-surface Cal/Val



Sea-surface infrastructure, Crete



CRS1 Cal/Val site (South-West Crete)



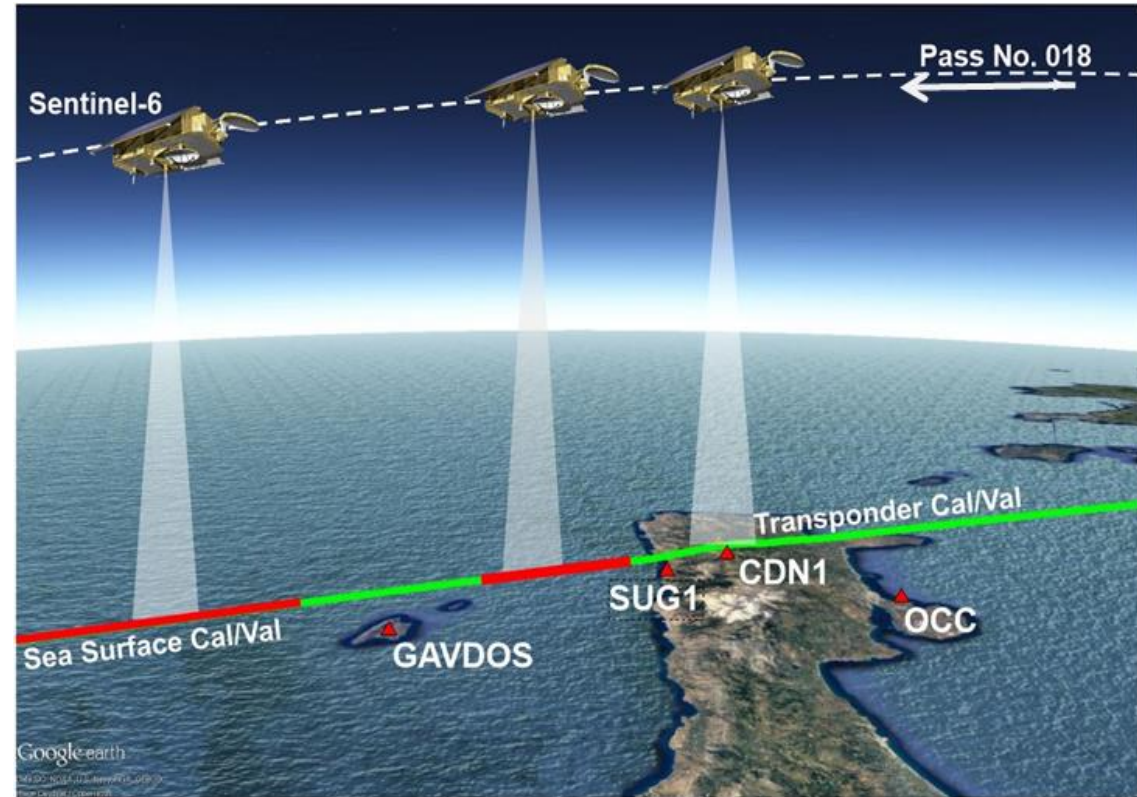
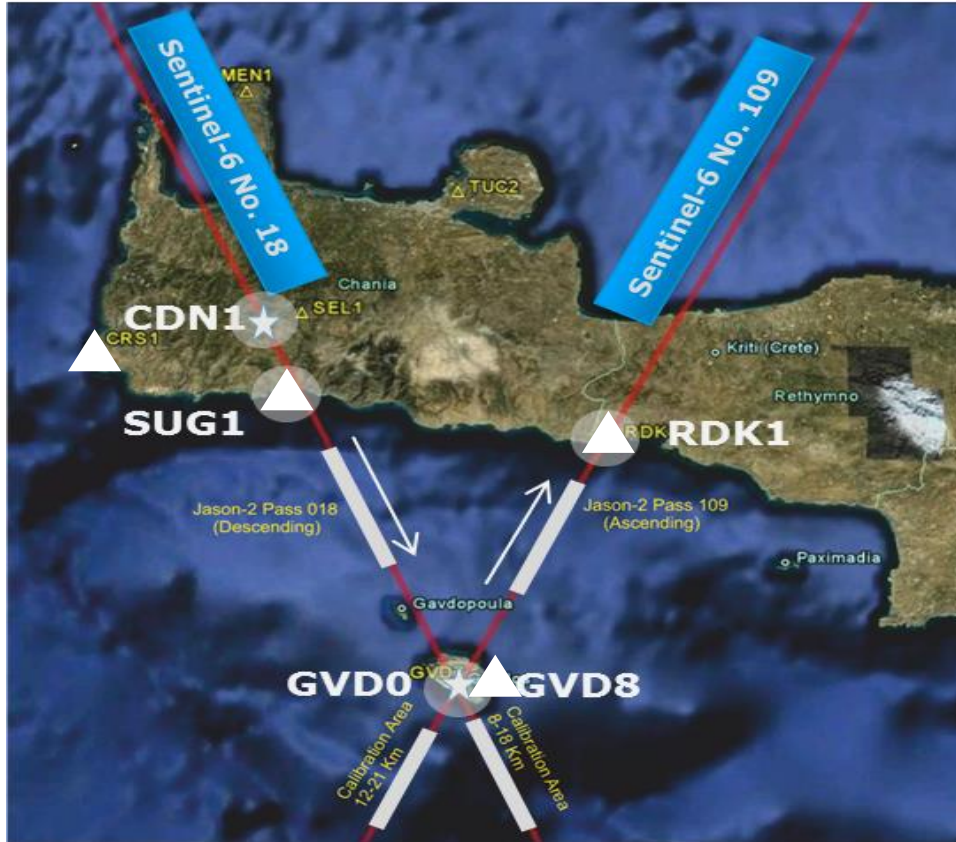
SUG1 Cal/Val site (South Crete)

Gavdos Cal/Val site



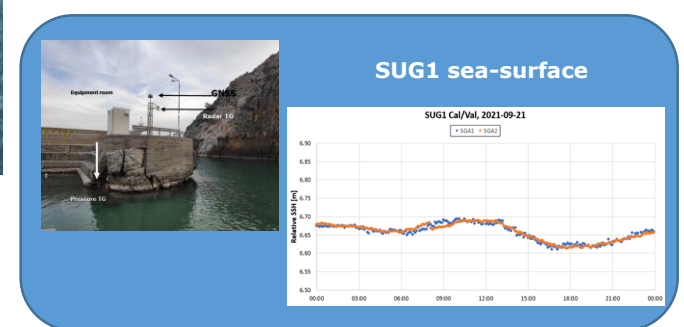
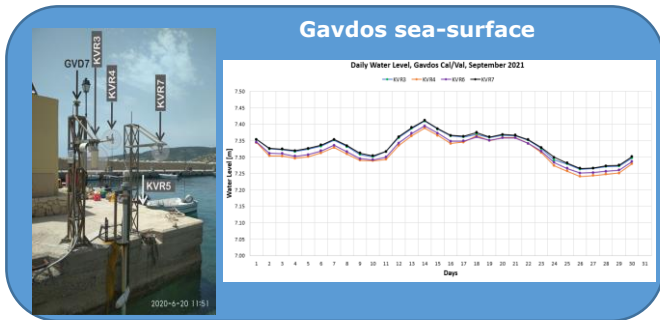
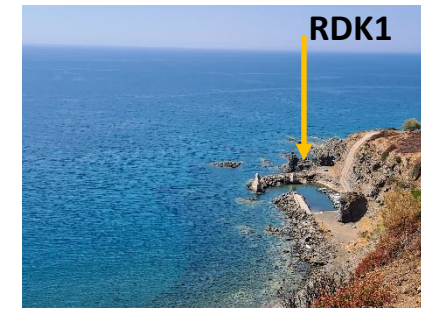
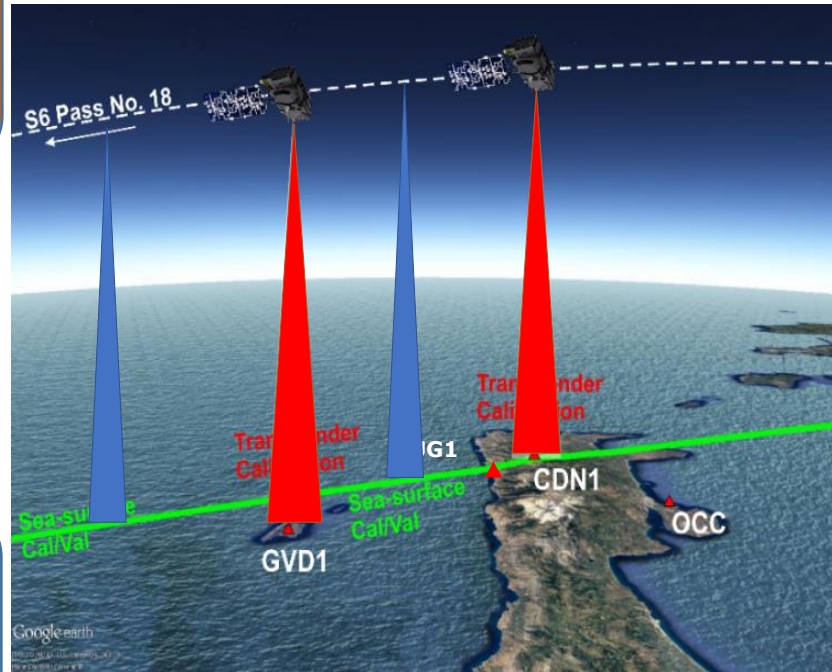
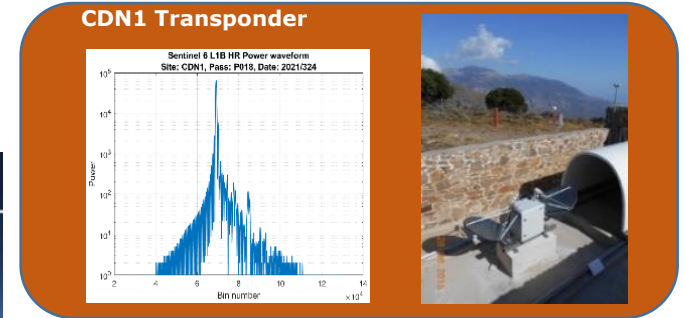
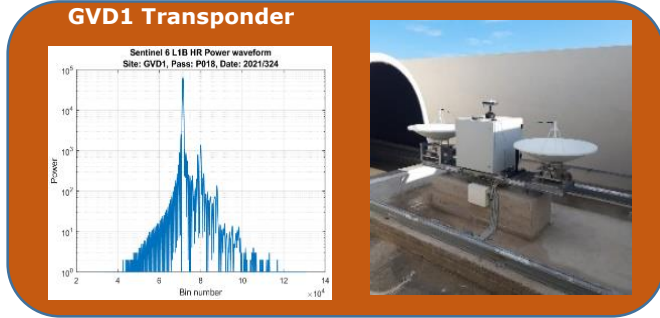
RDK1 Cal/Val site (South Crete)

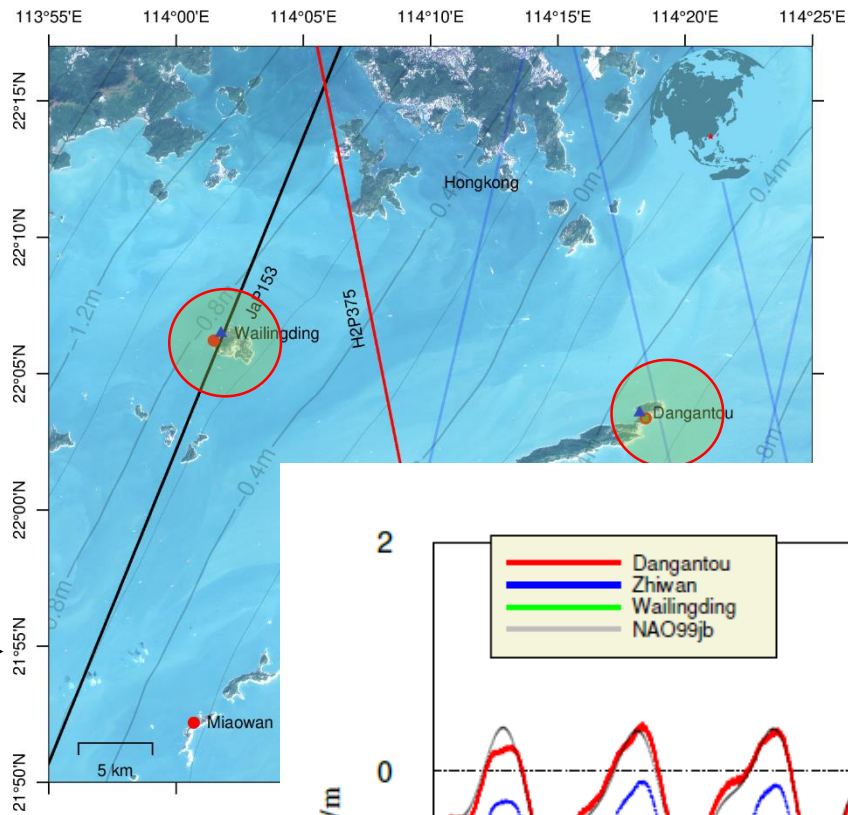
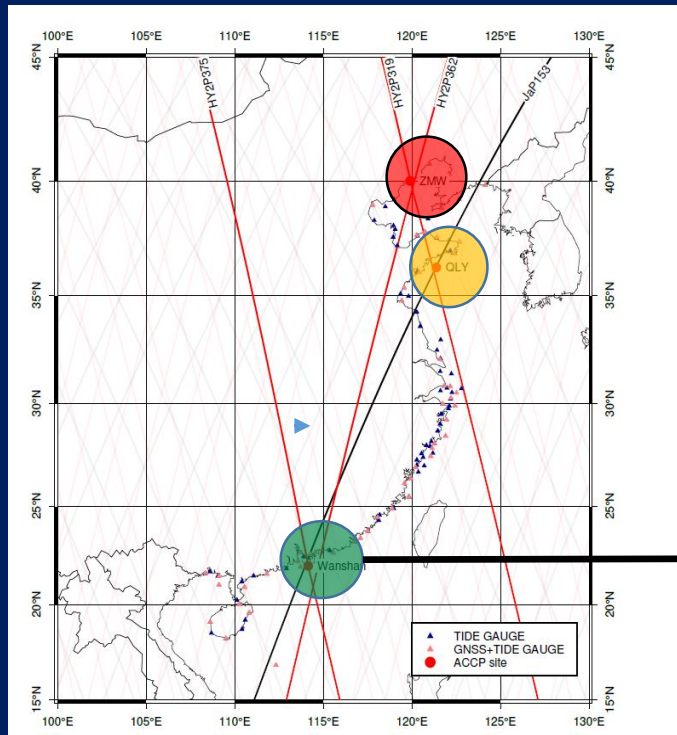
Transponders and sea surface Cal/Val sites at ESA PFAC, Crete



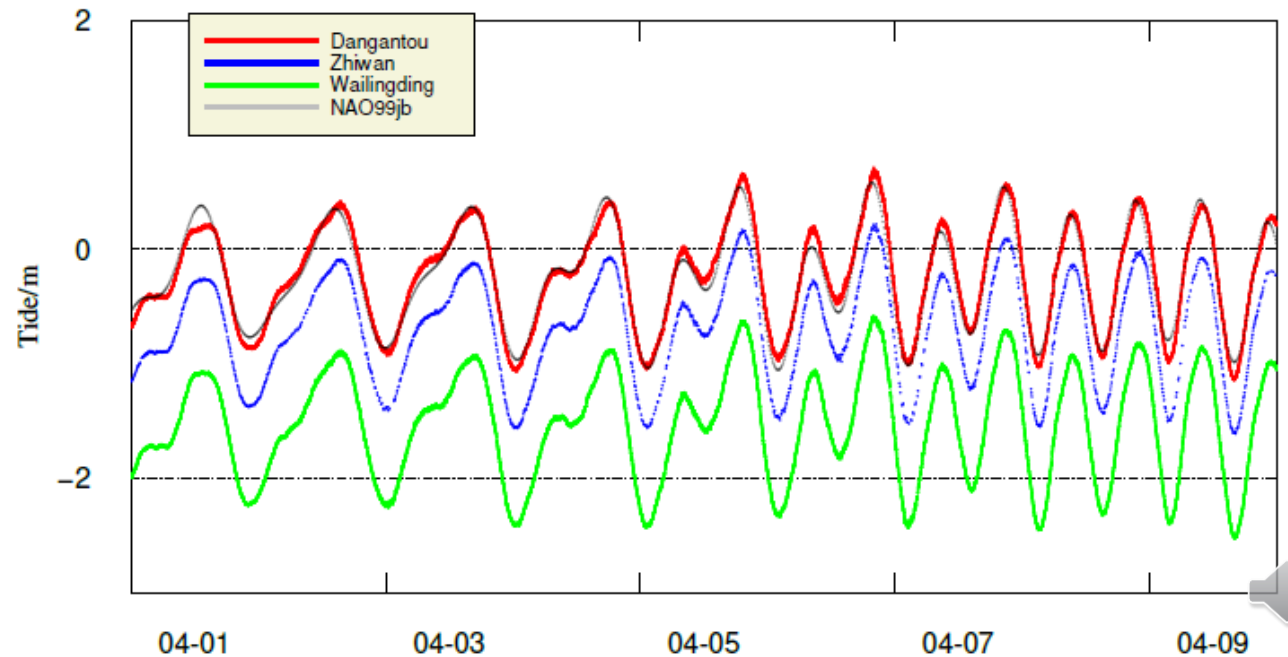
- ✓ 4 sea-surface & 2 transponder Cal/Val sites,
- ✓ Crossovers with S3A, S3B, JA3, S6, CryoSat-2, AltiKa, SWOT,
- ✓ Frequent (5 days), Redundant, Confident results, Directional errors.







ID	Cal/Val Site	Latitude	Longitude
QLY	Qianliyan (Qingdao)	121.385E	36.267N
ZMW	Zhimaowan (Bohai Sea)	119.920E	40.009N
Wanshan	Dangantou	114.303E	22.059N
Wanshan	Zhiwan	114.147 E	21.994
Wanshan	Wai Lingding	114.029E	22.108N



ESA Effort to (FRM4ALT):

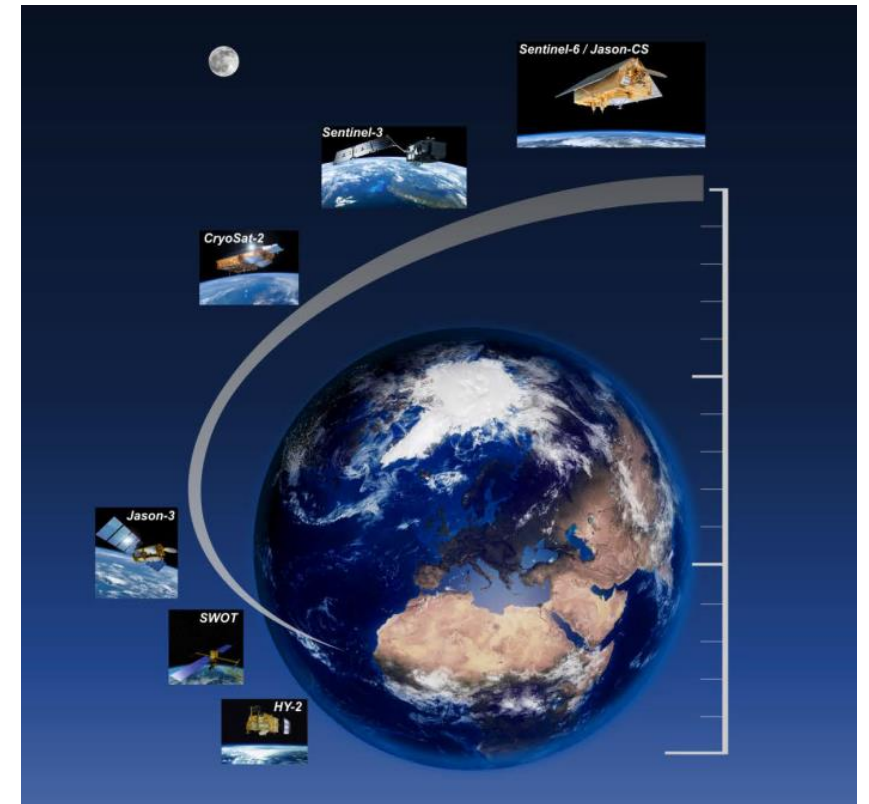
- Earth observation reliable in the long term,
- Comparable world-wide,
- Impervious to instrument, setting, location, conditions,
- Build up objective and reliable record for Climate Change,
- Achieve Uniform, Absolute Standardization of Earth observation,

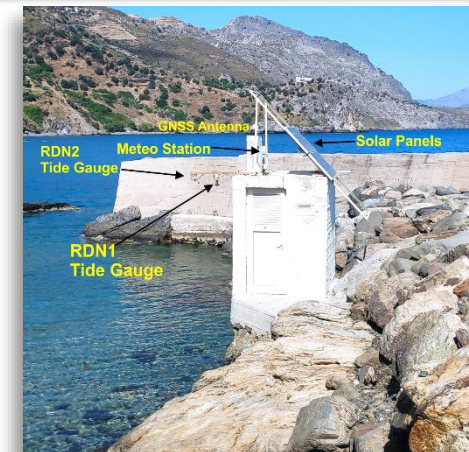
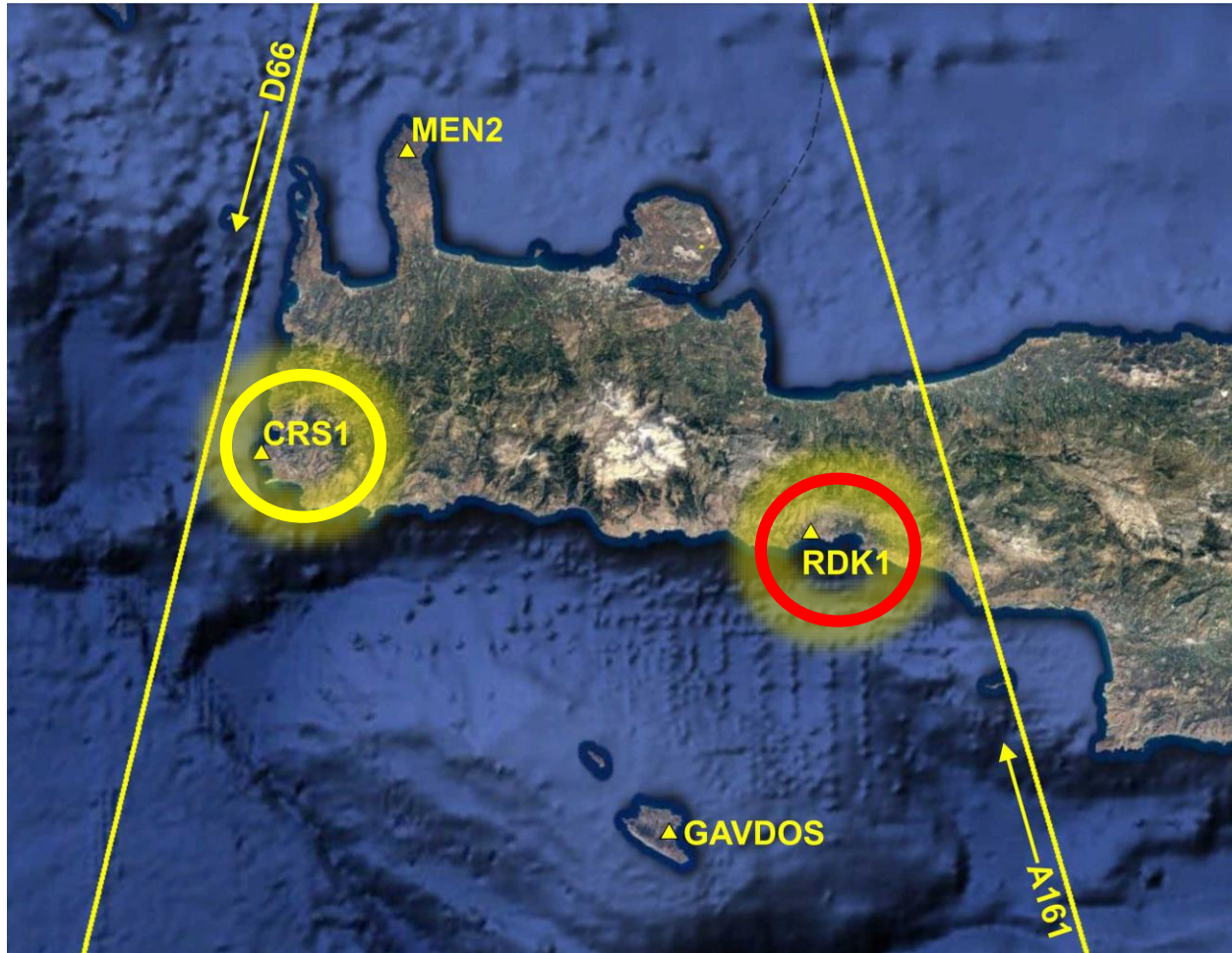
Why Need to Do that?:

- Place Trust on Earth data we produce;
- Communicate Correct information to Public (e.g., warnings);
- Right decisions for Policies in climate change & sea level change.

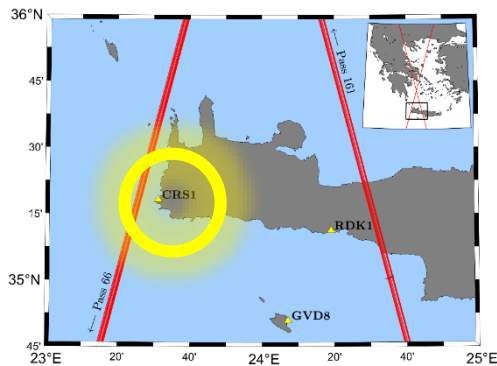
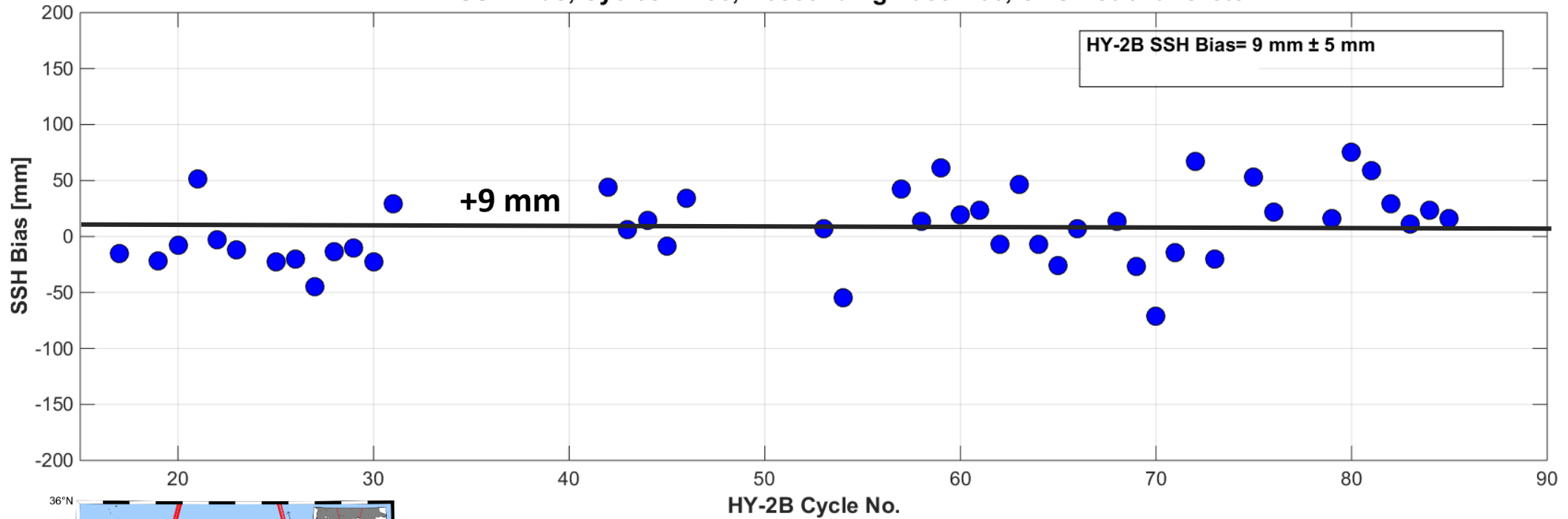
How to Achieve FRM for Altimetry Calibration?

- Connect Cal/Val to undisputed ground references,
- Evaluate each constituent contributing to Cal/Val uncertainty,
- Uncertainty on documented calibrations at reference sites,
- Uncertainty on metrology standards (speed of light, atomic time).

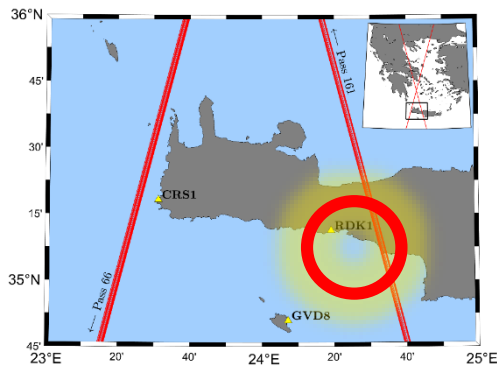
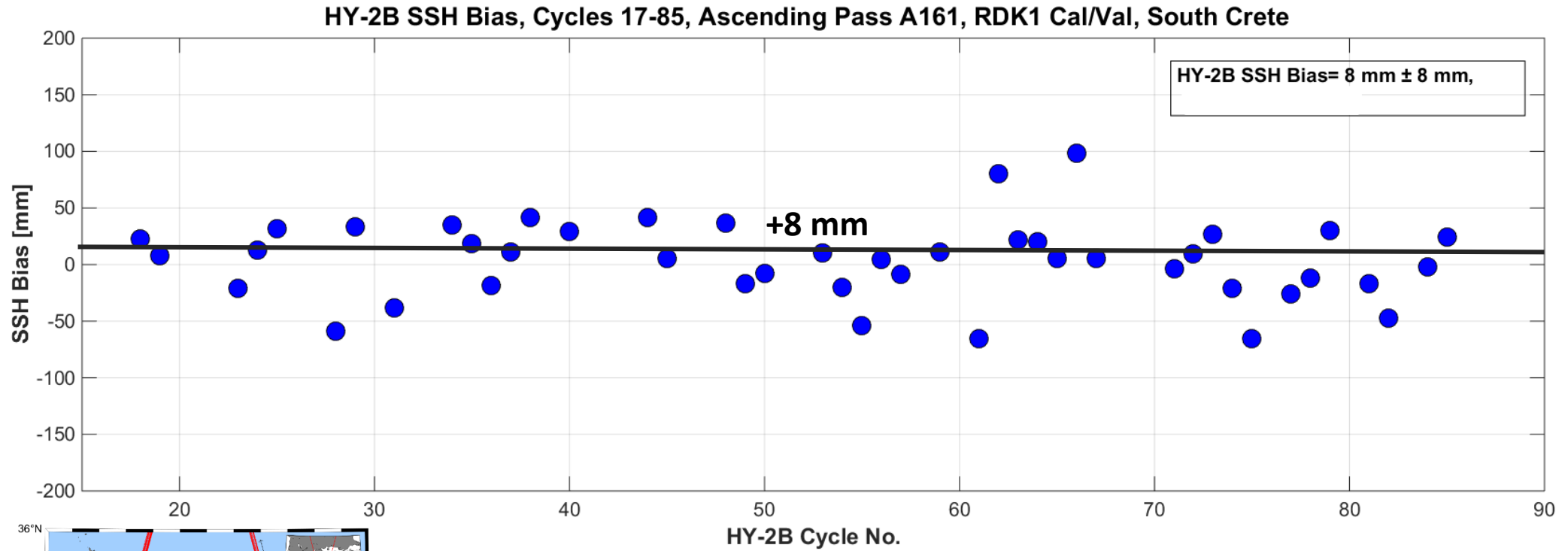




HY2-B SSH Bias, Cycles 17-86, Descending Pass D66, CRS1 Cal/Val Crete



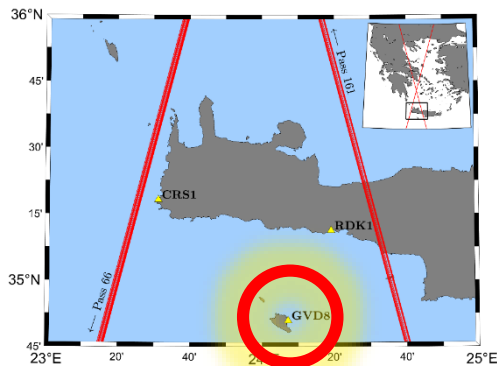
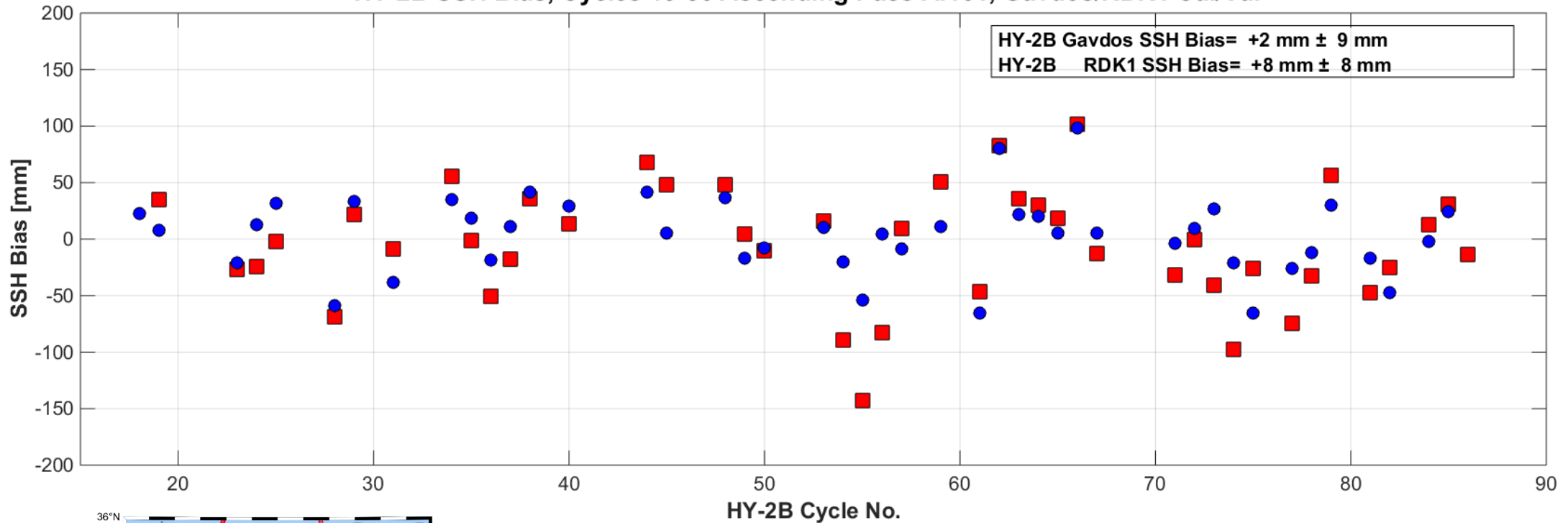
- HY-2B: Mean Bias: +9 mm ± 5 mm,
- FRM Uncertainty : ± 45 mm



- HY-2B: Mean Bias: +8 mm \pm 8 mm,
- FRM Uncertainty : \pm 50 mm

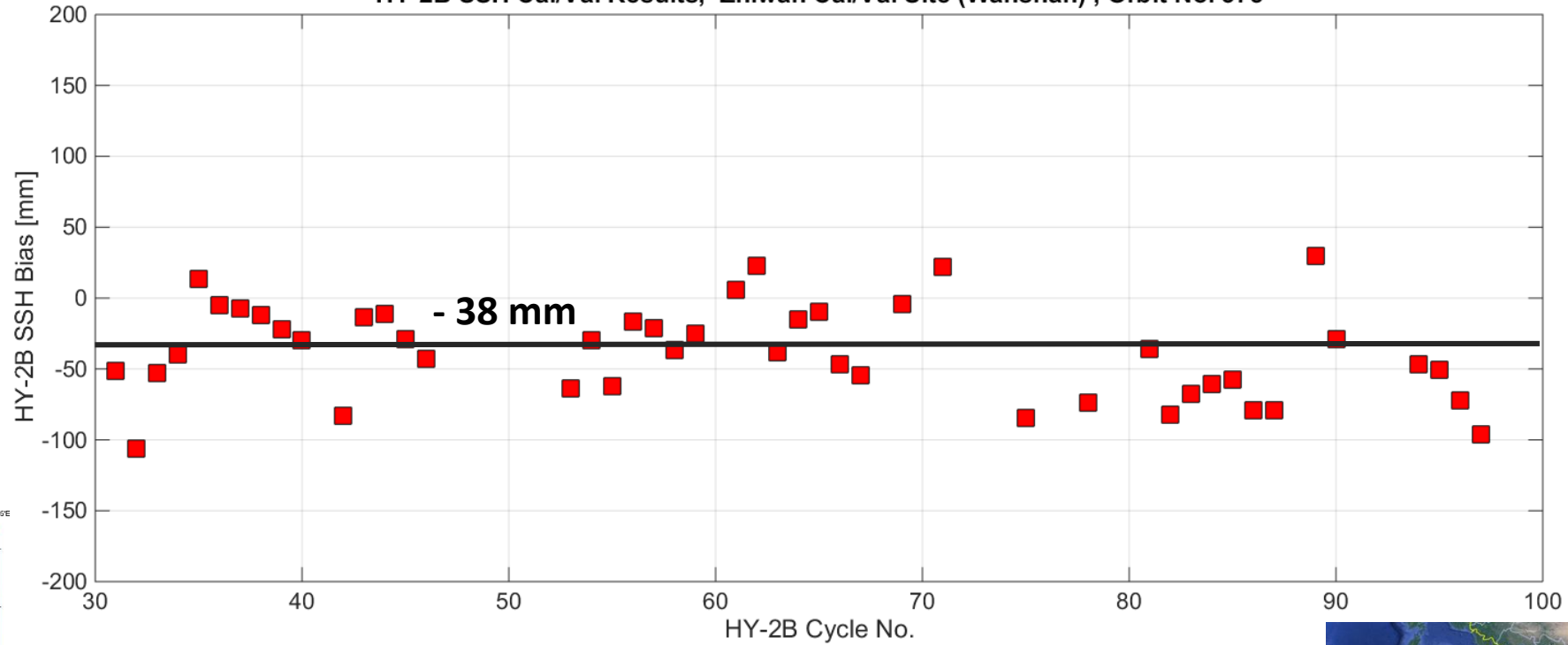


HY-2B SSH Bias, Cycles 19-86 Ascending Pass A.161, Gavdos/RDK1 Cal/Val

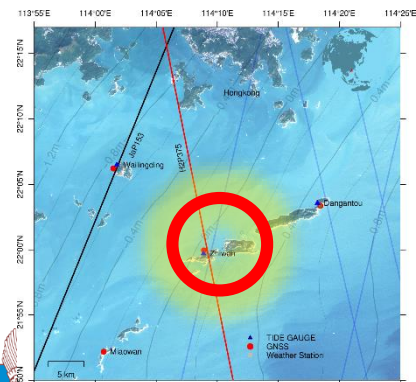


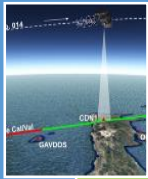
- HY-2B: Mean Bias: $+2 \text{ mm} \pm 9 \text{ mm}$,
- FRM Uncertainty : $\pm 50 \text{ mm}$

HY-2B SSH Cal/Val Results, Zhiwan Cal/Val Site (Wanshan) , Orbit No. 375



- HY-2B: Mean Bias: - 38 mm ± 3 mm,
- FRM Uncertainty : ± 50 mm





Site Selection

- Repeat Cycle
- Across-track distance
- Land contamination
- Water Depth
- Directional errors
- Multi-mission
- Reference surfaces
- Accessibility
- Security
- Ground stability
- Geodetic ties
- GNSS visibility
- Power supply & Communications



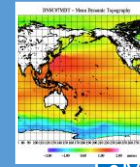
Absolute positioning

- Diverse GNSS satellites
- Diverse receivers & antennas
- Absolute GNSS antenna calibration
- 30s sampling rate
- 20 Hz high-rate ring buffer
- Reference frames
- Relative & absolute positioning
- Height diffs <2mm
- Diverse positioning systems (i.e., GNSS, DORIS, SLR, etc.)
- UTC time for time tagging
- At least 2-3 years of continuous operation.



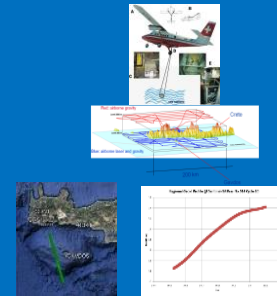
Atmospheric Delays

- GNSS-Derived ionospheric & zenith tropospheric delays at the time of satellite overpass
- Operation of meteo sensors
- Validation w.r.t. global/regional modeling
- Radiosondes, photometers, radiometers measurements
- OLCI observations.



Geophysical effects

- Models for earth tides (solid earth, ocean tidal loading, pole tide) shall follow IERS conventions
- Establish reference geoid, MSS, MDT surfaces
- Validate reference surface with local/regional marine/aerial/terrestrial surveys



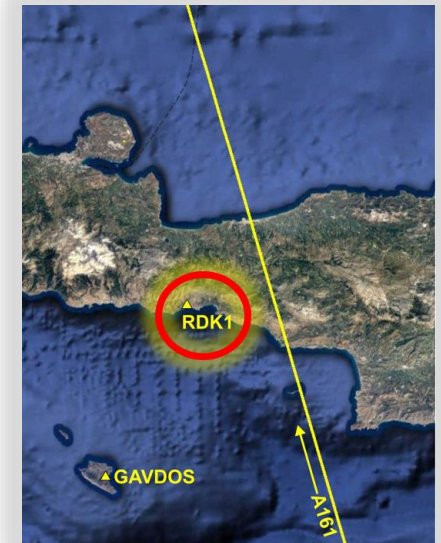
Water level determination

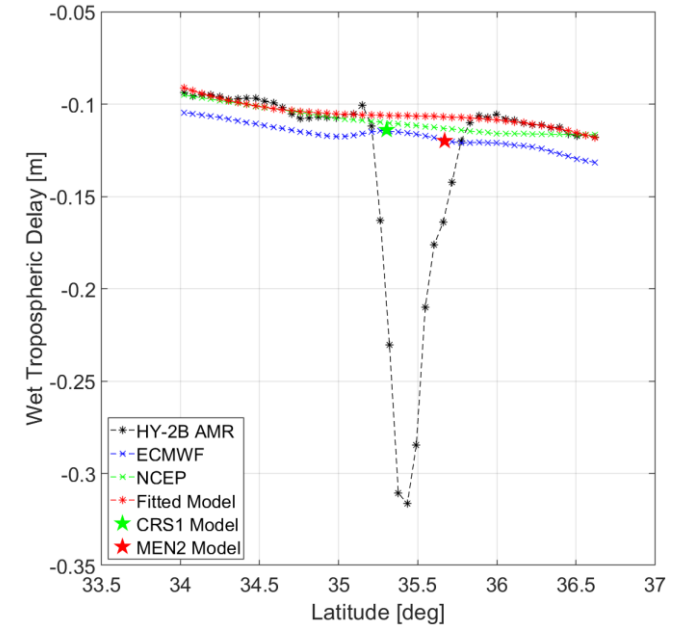
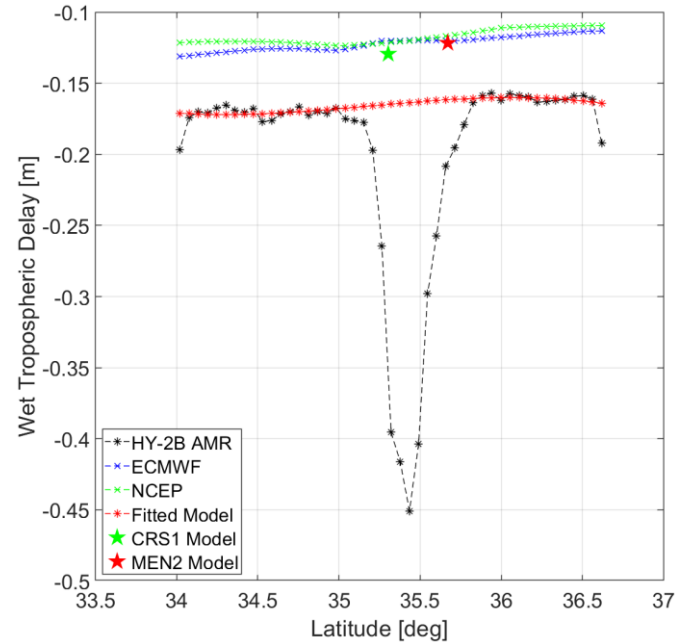
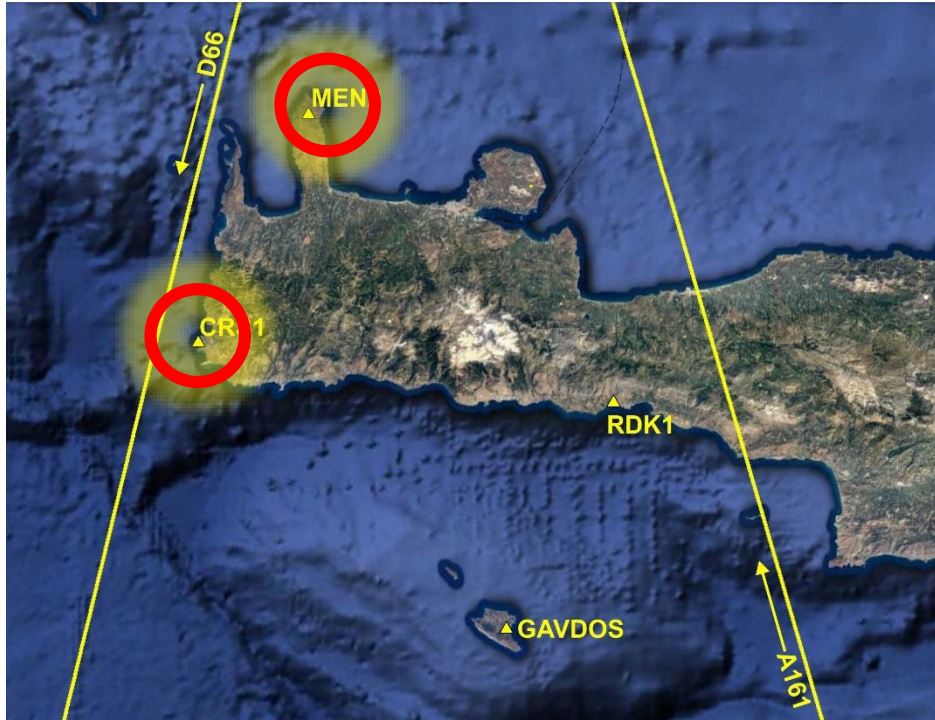
- Multiple (at least three) tide gauges of diverse measuring principle (radar, acoustic, pressure, floating).
- Geodetic ties between GNSS and tide gauge sensors via spirit leveling surveys with ± 1 mm
- Calibration certificates from manufacturers for repeatability, reproducibility, hysteresis, drift, non-linearity, etc.
- Validation of instrument's performance, by the Cal/Val site operator, prior its permanent installation
- Field validation experiments to be conducted at least every 6 months using a reference instrument
- Relative field calibration between operating tide gauges
- At least 1 hour of water level reading centered to the satellite overpass time of closest approach.





Description	CRS1	RDK1
Tide gauge Sensor	± 4 mm	± 6 mm
Repeatability	± 2.53 mm	± 2.53 mm
Zero-point reference	± 2.50 mm	± 2.50 mm
GNSS Receiver	± 3.46 mm	± 3.46 mm
GNSS Repeatability	± 0.08 mm	± 0.09 mm
GNSS ARP	± 4.04 mm	± 4.04 mm
GNSS Solution	± 0.08 mm	± 0.13 mm
GNSS Velocity	± 1.96 mm	± 4.55 mm
GNSS Integration	± 3.75 mm	± 3.75 mm
Control Ties	± 3.75 mm	± 3.75 mm
Reference Surfaces	± 42.00 mm	± 47.00 mm
Final Water Level	± 7.50 mm	± 7.50 mm
Geoid Slope	± 5.77 mm	± 5.77 mm
Processing	± 0.29 mm	± 0.29 mm
Unaccounted Effects	± 11.55 mm	± 11.55 mm
Uncertainty Budget	± 45.41 mm	± 50.44 mm





Difference	Average	σ
HY-2B AMR – CRS1(GNSS)	-7 mm	± 27 mm
HY-2B AMR – MEN2 (GNSS)	+7 mm	± 30 mm
HY-2B AMR – ECMWF	+ 3 mm	± 24 mm
HY-2B AMR – NCEP	-13 mm	± 25 mm



- European Young Researchers:
- **Costas Kokolakis**, PhD candidate;
- **Dr. Dimitrios Piretzidis**, Post-Doc researcher.
- Upgrade the SSH Altimeter Calibration Techniques;
- Design, Manufacture, Establish at a proper ground site a Corner Reflector for sigma-0 Altimeter Calibration;
- Determine Uncertainty on FRM Strategy.

Name	Institution	Poster title	Contribution
Constantine Kokolakis	Technical University of Crete, Greece	Absolute Calibration of σ_0 for European and Chinese Satellite Altimeters using Passive Corner Reflectors	First steps and tests for design, implementation and validation of corner reflectors for absolute sigma-naught calibration of satellite altimeters.





- Continue Calibration of European and Chinese altimeters;
- Analyze FRM Uncertainty at Chinese Cal/Val;
- Extend Cal/Val to HY-2C, HY-2D, S6, ... Cal/Val;
- Cross-calibrate diverse missions;
- Calibration of HY-2 microwave radiometer;
- Joint Journal Publication is ready to be submitted.

